

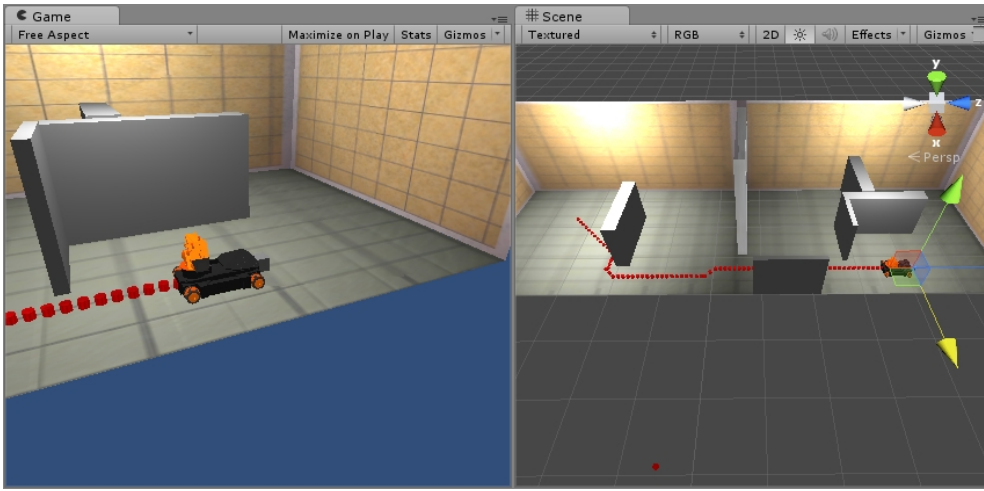
# LIS

## Laboratoire d'ingénierie des systèmes de Vers

### PROJET2 - MASTER2 CSER 2015

#### Interaction system for robotic in virtual environment

**Abstract** : Our project's aim is to design a decision system for robotic interaction in a virtual environment. The system manages to cope with its environment through virtual sensors that inform about what happens in order to act accordingly. All this is done using a knowledge base that describes the state of the environment. Models stored in the knowledge base are instantiated. Robot uses these models all over the mission and due to its decision system. At least depending on the situation and the events received of using the adequate model to execute a specific task.



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