



Laboratoire d'ingénierie des systèmes de Vers

WORKSHOPS 2010 - 2013 DE L'ÉQUIPE ROBOTIQUE INTERACTIVE

Workshops 2010 - 2013

2012

S. Bertrand, O. Bruneau, "Simulation of Highly Dynamic Locomotion with a Bipedal Robot: A Fast Running Algorithm", Dynamic Walking Conference, Pensacola, Florida, USA, May 21-24, 2012

2011

P.F. Doublier, O. Bruneau, F. B. Ouezdou, Crossing an obstacle by a biped robot with large inertia effects, Workshop on Humanoid and Legged Robots, HLR 2011, Paris, France, February 14-15, 2011.

O. Bruneau, "What is a relevant dynamic modeling for the anthropomorphic robots ? ",

Workshop invit  "Dynamic modeling and optimal control of humanoid robots ", 11th IEEE-RAS International Conference on Humanoid Robots, Humanoids11, October 26th - 28th, 2011, Bled, Slovenija.